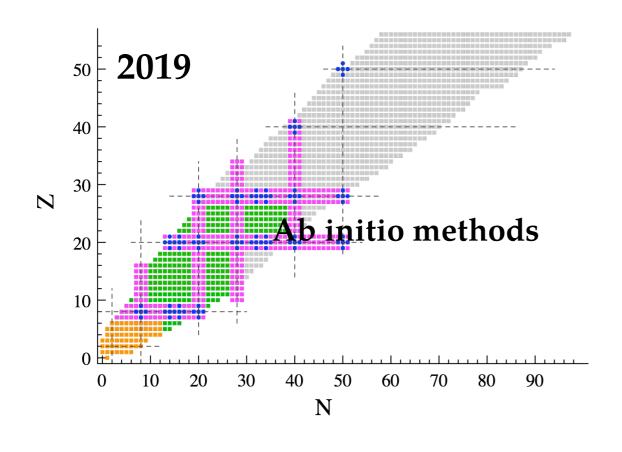
### High-Order Many-Body Bogoliubov Perturbation Theory



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2019 in preparation





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- Introduction
- Formalism
  - Wave-functions and observables
- Applications
  - O Resummed observables
  - *A posteriori* corrections
- Conclusions

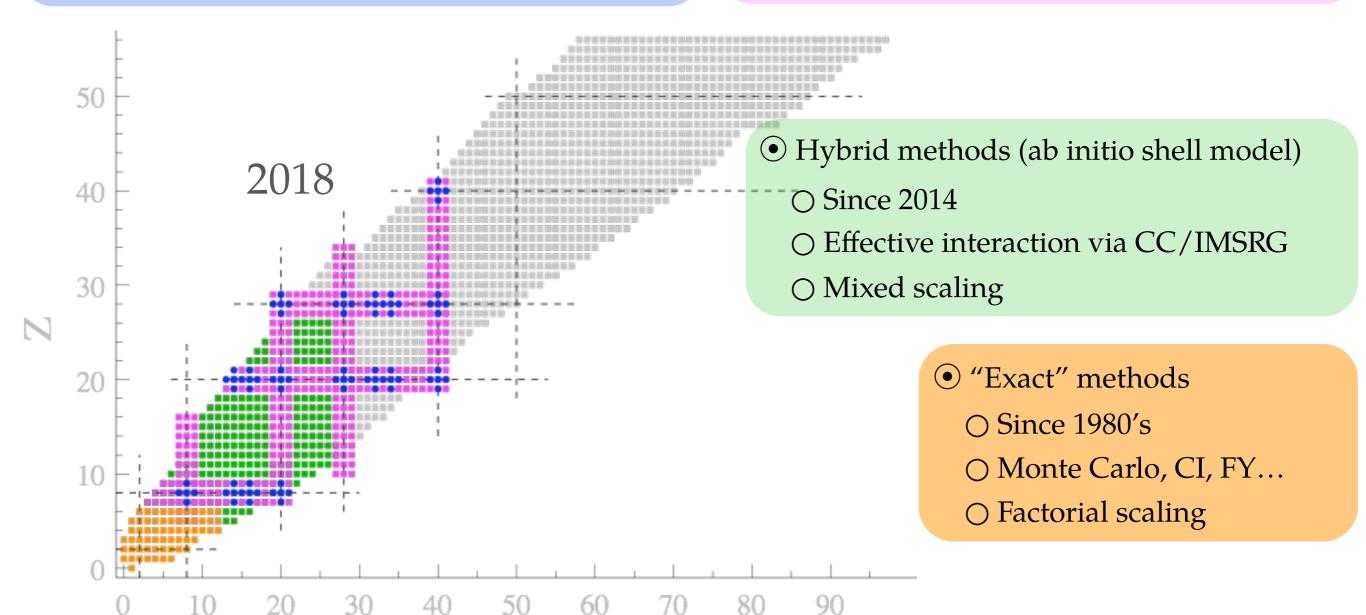
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### Ab initio nuclear chart

- Approximate methods for doubly closed-shells
  - Since 2000's
  - O MBPT, SCGF, CC, IMSRG
  - Polynomial scaling

- Approximate methods for singly open-shell
  - Since 2010's
  - O BMBPT, GGF, BCC, MR-IMSRG, MCPT
  - Polynomial scaling



## Single-reference expansion many-body methods

### **Many-body problem**

$$H|\Psi_k^A\rangle=E_k^A|\Psi_k^A\rangle$$
 A-Body Hamiltonian A-Body wave-function 5 variables, A nucleons

#### **U(1)** Symmetry

$$[H,A] = 0$$

## Single-reference expansion many-body methods

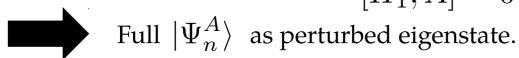
#### Many-body problem

#### **U(1)** Symmetry

$$[H, A] = 0$$

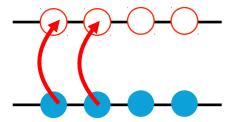
### Symmetry conserving expansion

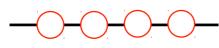
$$H = H_0 + H_1$$
 such that 
$$\begin{aligned} [H_0, A] &= 0 \\ [H_1, A] &= 0 \end{aligned}$$

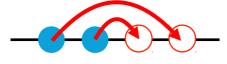


Closed-shell

Open-shell







Non-degenerate

Degenerate

Good starting point Improper starting point

## Single-reference expansion many-body methods

#### Many-body problem

A-Body wave-function U(1) Symmetry

$$[H,A] = 0$$

### Symmetry conserving expansion

$$H = H_0 + H_1$$
 such that  $[H_0, A] = 0$   
 $[H_1, A] = 0$ 

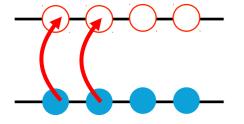


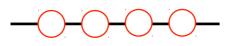
Full  $|\Psi_n^A\rangle$  as perturbed eigenstate.

Closed-shell

A-Body Hamiltonian  $H = T + V^{2N} + V^{3N} + \dots + V^{AN}$ 

Open-shell







### Symmetry breaking expansion

$$H = H'_0 + H'_1$$
 such that

5 variables, A nucleons

$$[H'_0, A] \neq 0$$
$$[H'_1, A] \neq 0$$

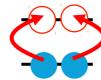
Open-shell



Static / dynamical correlations



• Polynomial cost at given order



Truncated expansions break symmetry

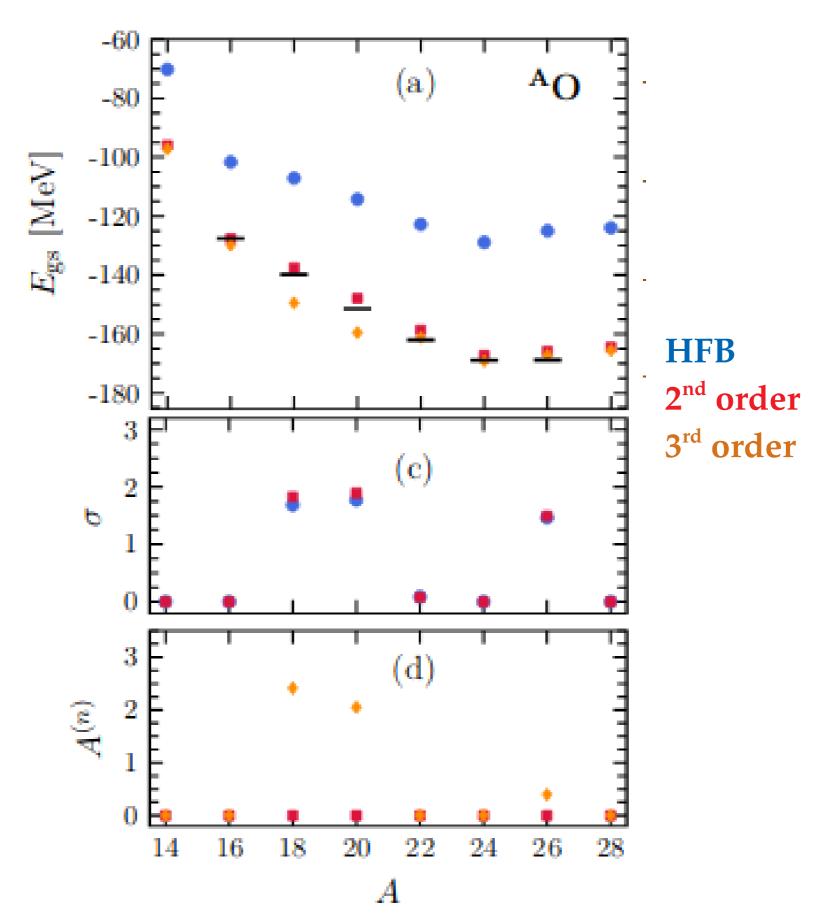
Non-degenerate

**Degenerate** 

Non-degenerate

Good starting point Improper starting point Proper starting point

### Particle number corrections in BMBPT



## High order constrained BMBPT

#### **Constrained BMBPT**

- Constrain average A at each order P.
- Convergence?

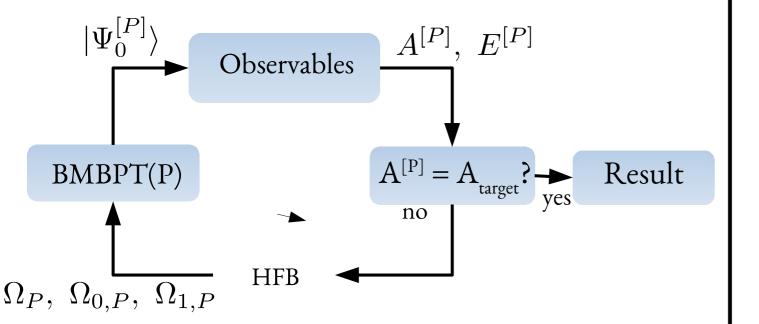
#### Workaround

- Numerically costly.
- *A posteriori* correction.

#### **Toward high orders**

- Series behavior? => resummation
- Particle number asymptotic restoration?
- Check low orders

#### **Order P constraint**



#### Intrisincally iterative

Particle number adjusted at each working order P.

#### **Truncation**

$$\mathcal{H}^1$$
  $\mathcal{H}^N$   $e_{max} 2, 4, 6$   $SD(T)(Q)$ 

Building

CI Matrix.

#### **Toy Model / Proof of principle**

Realistic interaction

Far from model space convergence

CI truncation contamination at high order

More informations than standard MBPT

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## Time independent (un)constrained BMBPT

$$\{a, a^{\dagger}\} \to \{\beta, \beta^{\dagger}\} \qquad \qquad \Omega_P \equiv \Omega_{0,P} + \Omega_{1,P}$$

$$|\Phi_P^{k_1 k_2 \cdots}\rangle \equiv \beta_{k_1}^{\dagger} \beta_{k_2}^{\dagger} \cdots |\Phi_P\rangle \qquad \qquad \Omega_P(x) \equiv \Omega_{0,P} + x\Omega_{1,P}$$

$$H \to \Omega_P \equiv H - \lambda_P A \qquad \qquad x \in [0, 1]$$

$$\Omega_P(x)|\Psi_{n,P}(x)\rangle = \tilde{\mathcal{E}}_{n,P}(x)|\Psi_{n,P}(x)\rangle$$

## Time independent (un)constrained BMBPT

$$\{a, a^{\dagger}\} \rightarrow \{\beta, \beta^{\dagger}\}$$

$$|\Phi_P^{k_1 k_2 \cdots}\rangle \equiv \beta_{k_1}^{\dagger} \beta_{k_2}^{\dagger} \cdots |\Phi_P\rangle$$

$$H \to \Omega_P \equiv H - \lambda_P A$$

$$\Omega_P \equiv \Omega_{0,P} + \Omega_{1,P}$$

$$\Omega_P(x) \equiv \Omega_{0,P} + x\Omega_{1,P}$$
$$x \in [0,1]$$

$$\langle \Phi_n | \Phi_n^{(p)} \rangle \equiv \delta_{np}$$

$$\tilde{\mathcal{E}}_{n,P}^{(p)} = \langle \Phi_{n,P}^{(0)} | \Omega_{1,P} | \Phi_{n,P}^{(p-1)} \rangle 
|\Phi_{n,P}^{(p)} \rangle = \left( \Omega_{P}^{00} + \sum_{k \in n} E_{k} - \Omega_{0,P} \right)^{-1} \left[ \Omega_{1,P} | \Phi_{n,P}^{(p-1)} \rangle - \sum_{1 \leq j \leq p} \tilde{\mathcal{E}}_{n,P}^{(j)} \Phi_{n,P}^{(p-j)} \rangle \right]$$

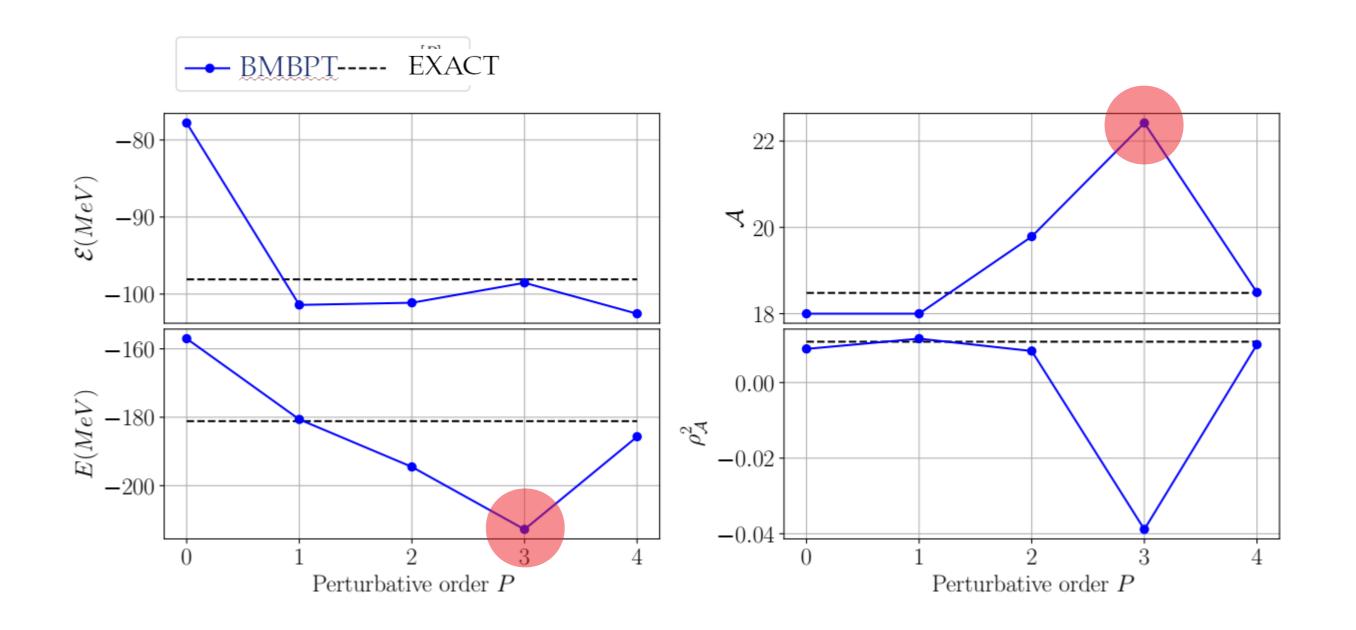
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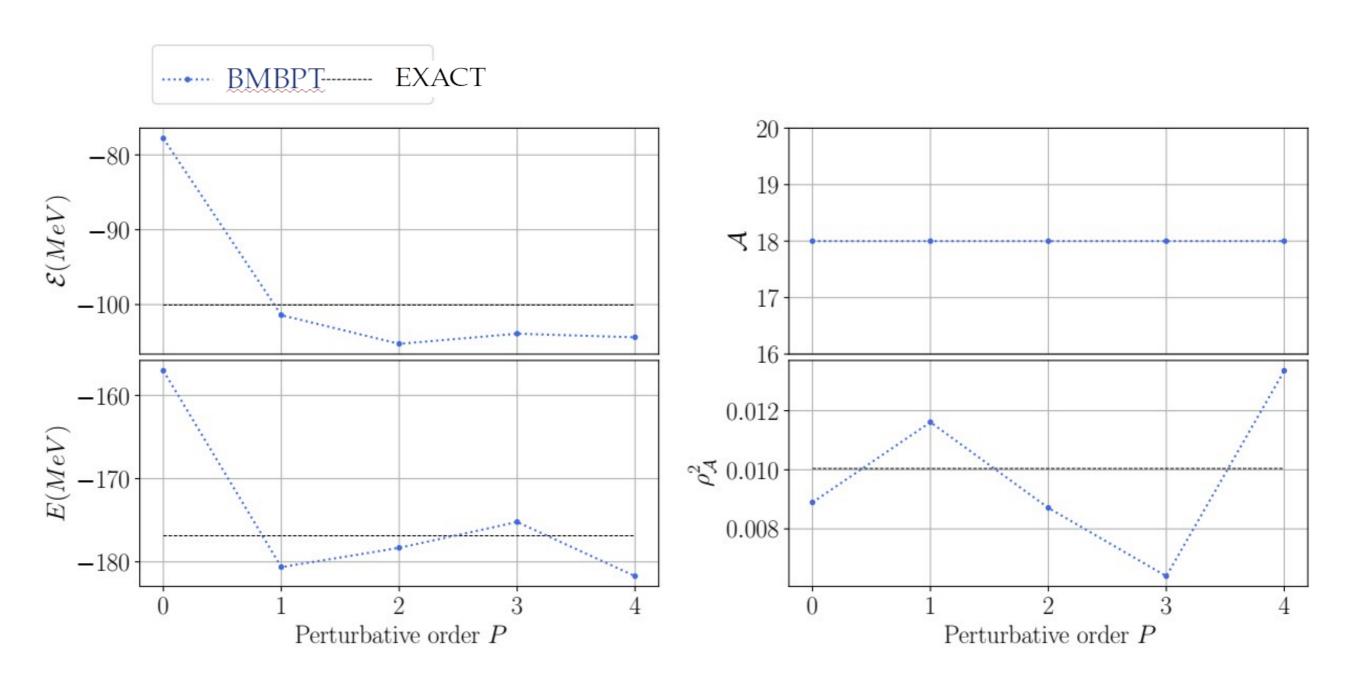
O18, Emax 4, SDT + IT

- $\bigcirc$  *A posteriori* corrections
- Conclusions

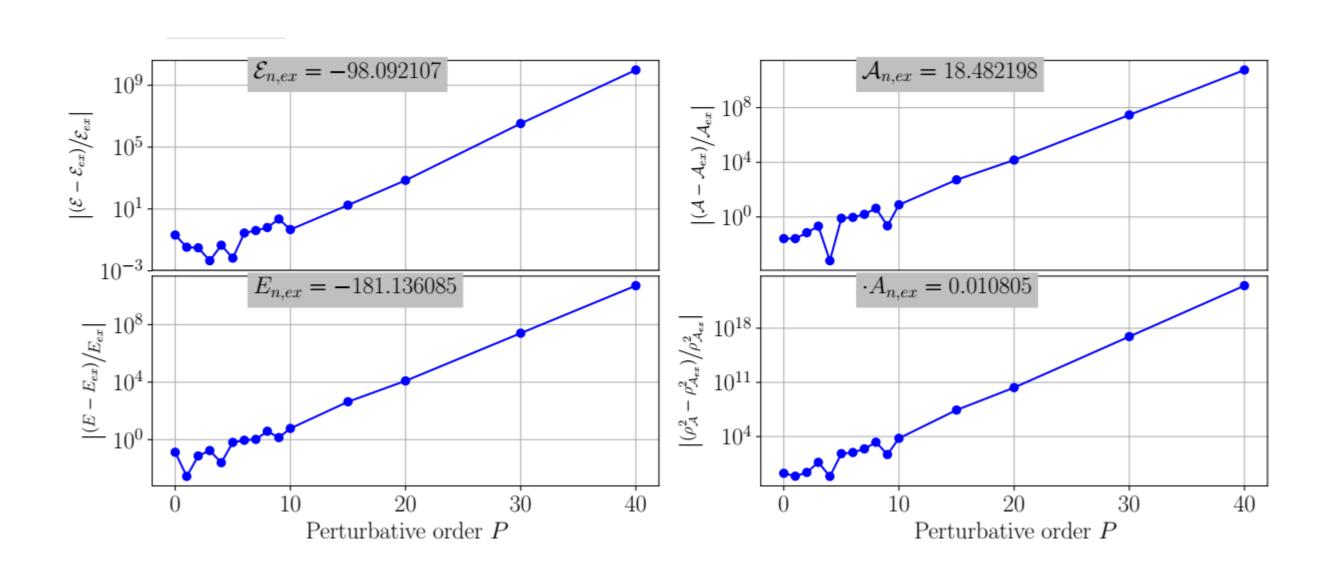
## First results of unconstrained BMBPT



## Constrained BMBPT Taylor series

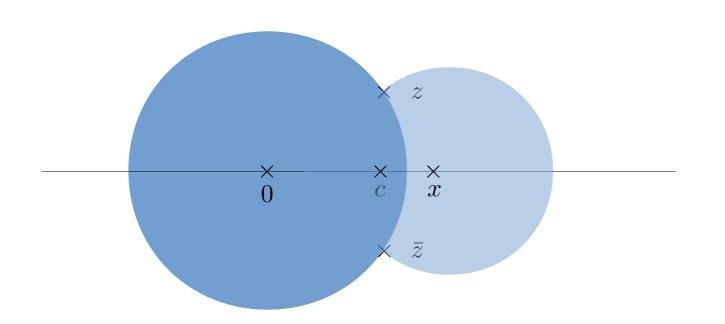


## But series are diverging...



## Analytic continuation

Dillon Frame et al. Phys. Rev. Lett 121.3 (2018) arXiv: 1711.07090



$$|\Psi(c)\rangle = \sum_{n} \frac{c^n}{n!} |\Psi^{(n)}(0)\rangle$$

$$|\Psi(x)\rangle = \sum_{m} \frac{(x-c)^m}{m!} |\Psi^{(m)}(x)\rangle$$

$$|\Psi(x)\rangle = \sum_{nm} \frac{(x-c)^m c^n}{n!m!} |\Psi^{(m+n)}(0)\rangle$$

## Eigen-vector continuation

D. K. Frame et al. Phys. Rev. Lett 121.3 (2018) arXiv: 1711.07090

 $|\Psi_n^{[P]}(x)\rangle$ visits a small space and is converging for small x

$$0 < x_0 < \cdots < x_P \ll 1$$

Extrapolate  $|\Psi_n^{[P]}\rangle$  by diagonalizing  $\Omega$  on  $|\Psi_n^{[P]}(x_0)\rangle, \cdots, |\Psi_n^{[P]}(x_P)\rangle$  or equivalently on  $|\Phi_n^{(0)}\rangle, \cdots, |\Phi_n^{(P)}\rangle$ 

$$\mathbf{\Omega}_{ij,P} \equiv \langle \Phi_{n,P}^{(i)} | \Omega | \Phi_{n,P}^{(j)} \rangle$$
 $\mathbf{N}_{ij,P} \equiv \langle \Phi_{n,P}^{(i)} | \Phi_{n,P}^{(j)} \rangle.$ 

Generalized

$$N_{ij,P} \equiv \langle \Phi_{n,P}^{(i)} | \Phi_{n,P}^{(j)} \rangle.$$

Eigenvalue Problem

$$\Omega X = \lambda N X.$$

#### **Ground state**

$$|\bar{\Psi}_{0,P,EC}^{[P]}(x)\rangle \equiv \operatorname{argmin}_{|\Psi\rangle \in \mathcal{K}_0^P} \frac{\langle \Psi | \Omega_P | \Psi \rangle}{\langle \Psi | \Psi \rangle}$$

P-order approx. of  $\Omega$  ground state connected to  $|\Phi_0\rangle$ 

#### **Excited states**

Not done here but reachable too.

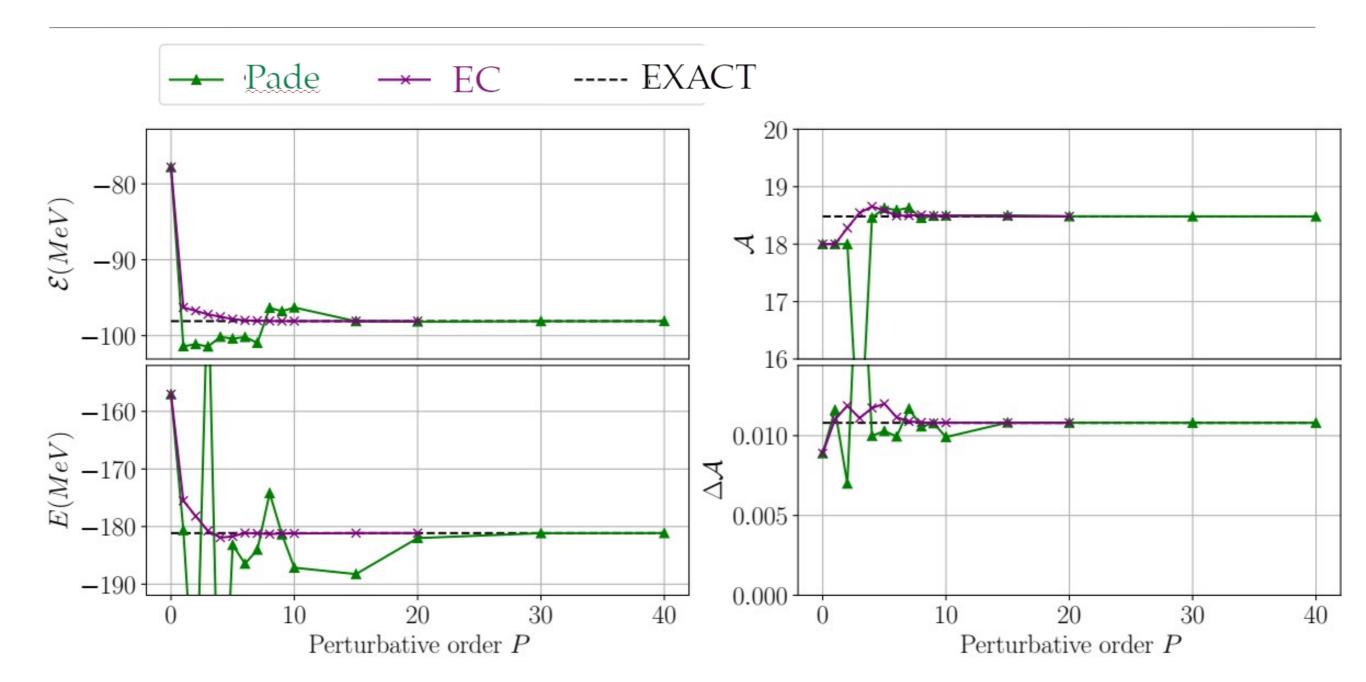
#### **Observables**

$$\mathcal{O}_{n,P,EC}^{[P]} \equiv rac{\langle \Phi_n | O | \Psi_{n,P,EC}^{[P]} \rangle}{\langle \Phi_n | \Psi_{n,P,EC}^{[P]} \rangle}$$

#### Remarks

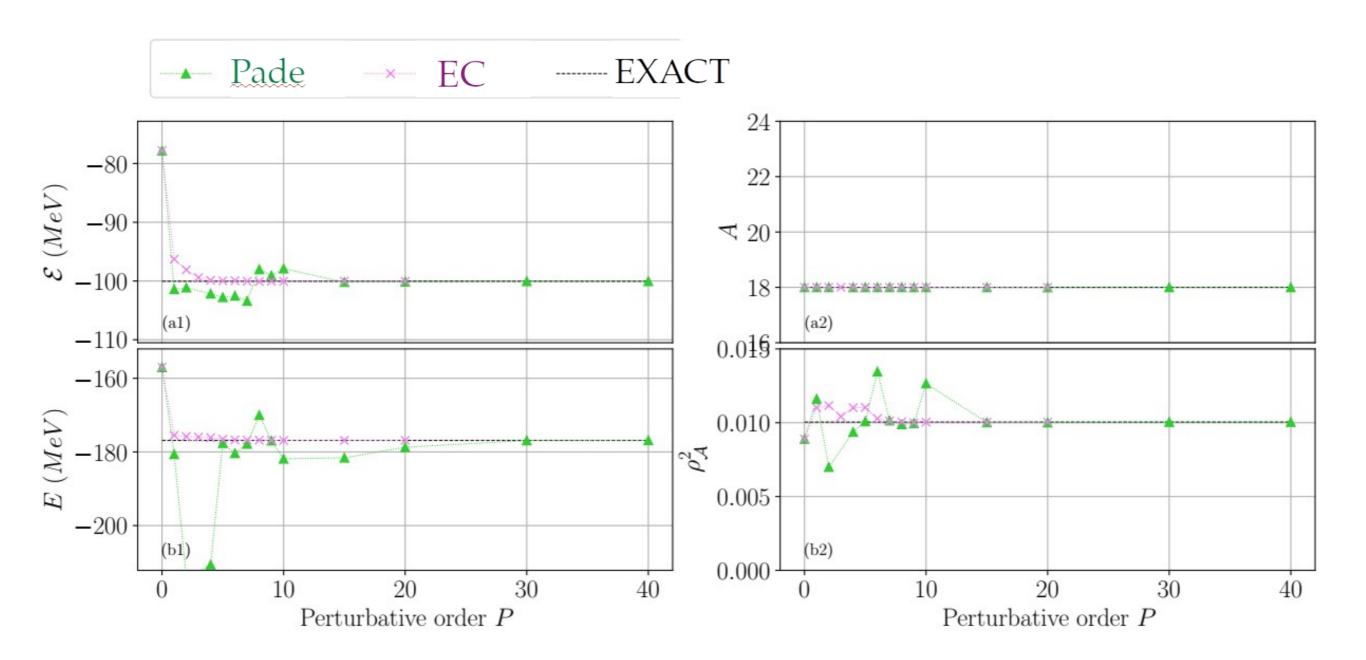
- No need of computing the vectors explicitly
- Increases complexity
- Valid also at low orders
- Variational: improves at each iteration

### Resummed observables in unconstrained BMBPT



Still wrong particle number even in the limit...

## **Constrained BMBPT**



## A posteriori correction

**Goal**: Correct for the discrepancy in average neutron / proton number without constraining at order P > 0

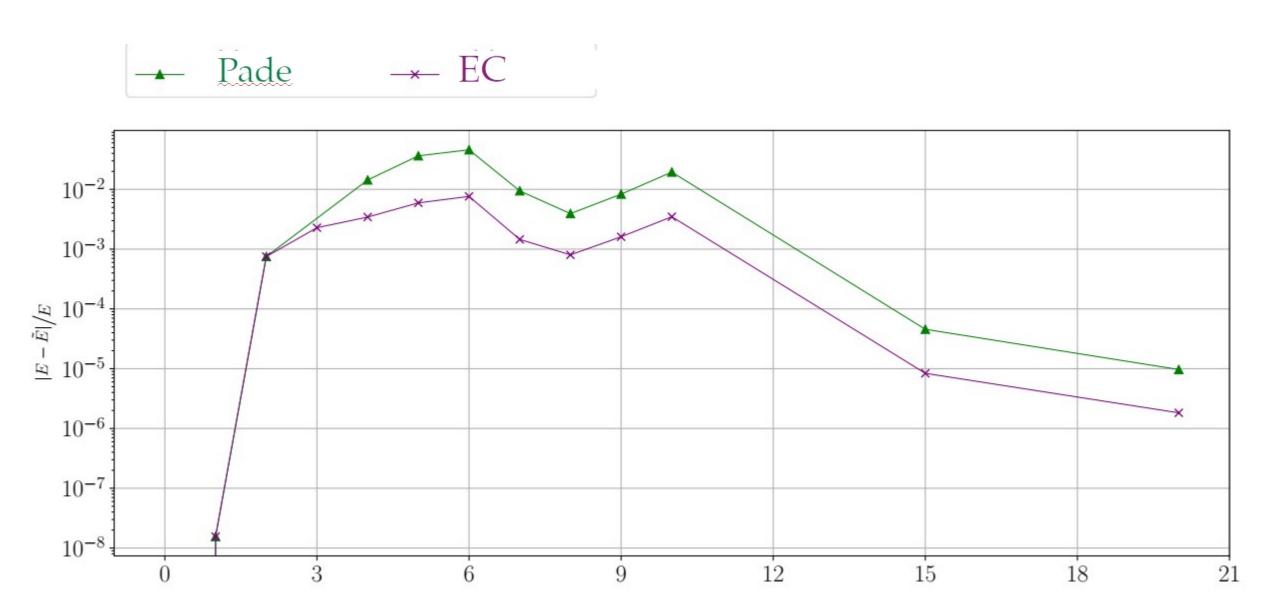
$$E_0^{[P]}\Big|_{A_0} = \mathcal{E}_0^{[P]} + \lambda A_0.$$

$$E_0^{[P]}\Big|_{A_0+\delta A} \approx E_0^{[P]}\Big|_{A_0} + \lambda \delta A$$

$$\tilde{E}_{0}^{P}\Big|_{A} \equiv E_{0}^{[P]}\Big|_{A^{[P]}} + \lambda \left(A - A^{[P]}\right) = \mathcal{E}_{0}^{[P]}\Big|_{A^{[P]}} + \lambda A$$

- No additional work (only one vacuum).
- Valid for small corrections.
- Apply to all computation methods of observables.
- Already used at order 3 in realistic calculations.

## Comparison with constrained BMBPT



Perturbative order P

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### Conclusion

#### Accurate results at low order

- Standard projective approach accurate (divergence at high order)
- Significant contamination to A appear early.

#### A posteriori corrections

- Accurate workaround to constrained BMBPT.
- No additional cost.

#### **Resummation techniques**

- Pade does not help at low order.
- Eigenvector continuation: promising result
- What about computational cost?
- Increases convergence rate.

#### **Particle number restoration**

- Need commutation between A and H...
- ... seem to appear at larger configuration space.
- SDT(Q)(P): higher order in PT with full operator.
- Underlines the need for projection techniques.

# Thanks for your attention

- Pepijn Demol
- Julien Ripoche
- Alexander Tichai
- Thomas Duguet
- Vittorio Somà







### Resummation of projective observables using Pade approximants

$$O_{n,P}^{[P]}(x) = \sum_{p=0}^P x^p \langle \Phi_{n,P}^{(0)}|O|\Phi_{n,P}^{(p)} \rangle$$
 How to deal with divergent partial sums at x=1?

$$\mathcal{O}(x) (= \sum o_i x^i) \qquad \qquad \mathcal{O}[M/N](x) = \left. \frac{\sum_{i=1}^M a_i x^i}{1 + \sum_{i=1}^N b_i x^i} \right. \text{ so that } \left. \frac{\mathrm{d}^k \mathcal{O}[M/N]}{\mathrm{d} x^k} \right|_{x=0} = \left. \frac{\mathrm{d}^k \mathcal{O}}{\mathrm{d} x^k} \right|_{x=0} \, \forall \, 0 \le k \le M+N.$$

$$\mathcal{O}\left[^{M/N}\right](x) \equiv \frac{\begin{vmatrix} o_{M-N+1} & o_{M-N+2} & \cdots & o_{M+1} \\ o_{M-N+2} & o_{M-N+3} & \cdots & o_{M+2} \\ \vdots & \vdots & \ddots & \vdots \\ o_{M} & o_{M+1} & \cdots & o_{M+N} \\ \sum_{i=0}^{M-N} o_{i} x^{N+i} & \sum_{i=0}^{M-N+1} o_{i} x^{N+i-1} & \cdots & \sum_{i=0}^{M} o_{i} x^{i} \\ \hline \begin{vmatrix} o_{M-N+1} & o_{M-N+2} & \cdots & o_{M+1} \\ o_{M-N+2} & o_{M-N+3} & \cdots & o_{M+2} \\ \vdots & \vdots & \ddots & \vdots \\ o_{M} & o_{M+1} & \cdots & o_{M+N} \\ x^{N} & x^{N-1} & \cdots & 1 \end{vmatrix}}.$$

**Unconstrained:** resummation of the projective truncated series.

**Constrained:** resummation of the partial sum at each order.

#### **Remarks:**

- Captures poles in the complex plane.
- Efficient at high order only: instabilities.
- No extra work: post-treatment only.

## Importance truncation

